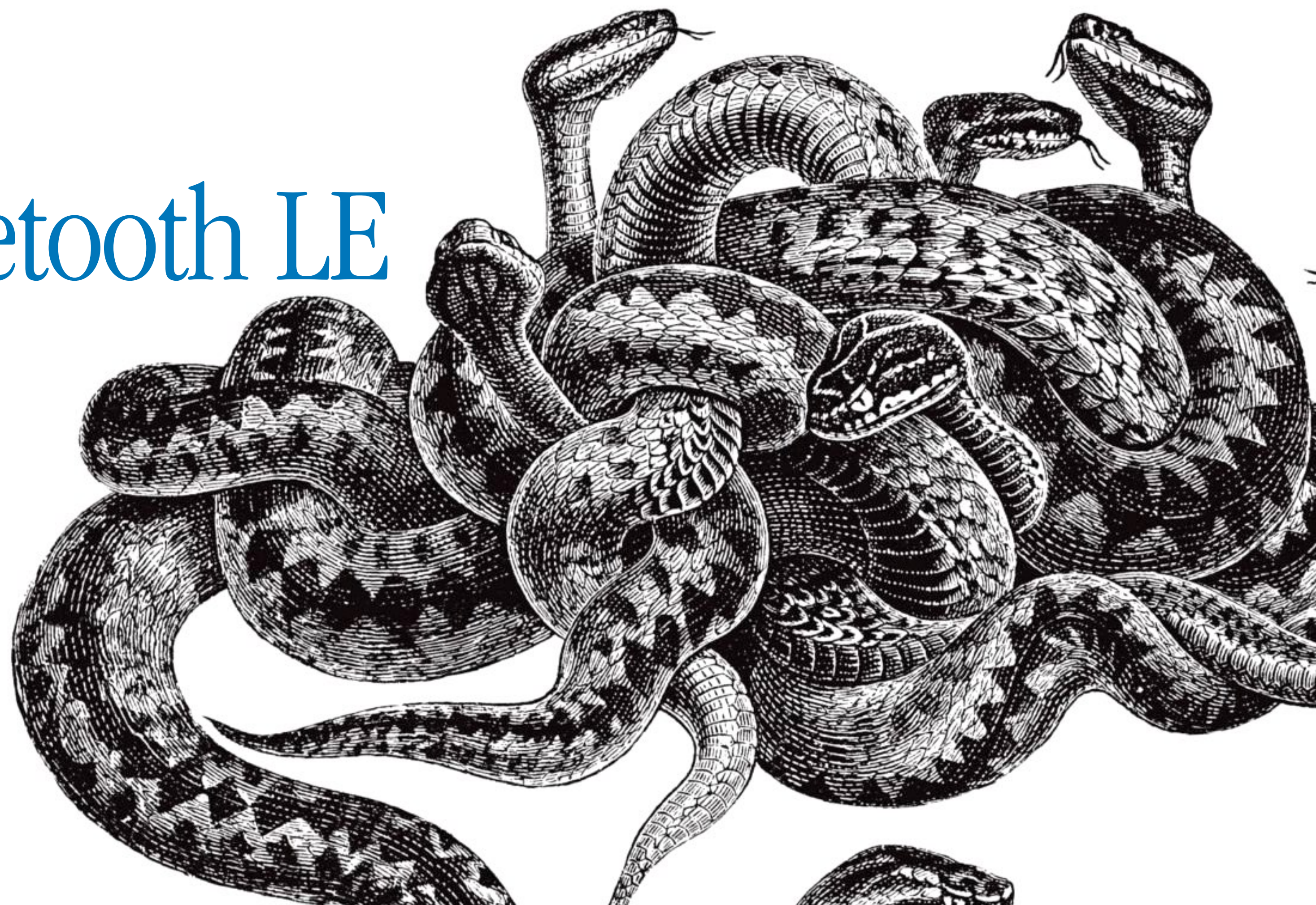


# Non solo blink: MicroPython e Bluetooth LE

Giacomo Vallorani  
25 Ottobre 2025



# Su di me



## Giacomo Vallorani

- Backend Software Engineer @ PagoPA
- Maker nel tempo libero
- Sistemi distribuiti e IoT

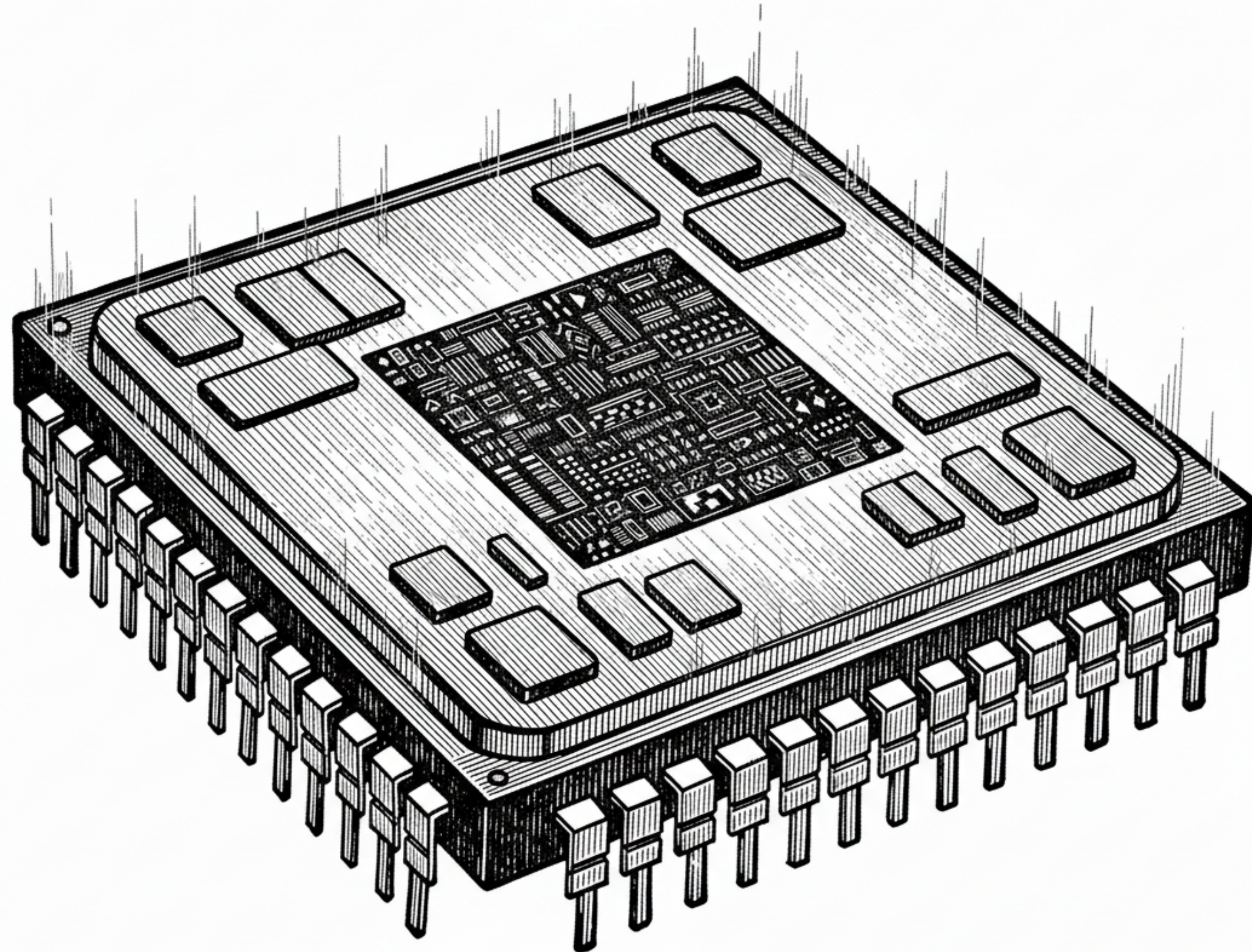


@Vallasc

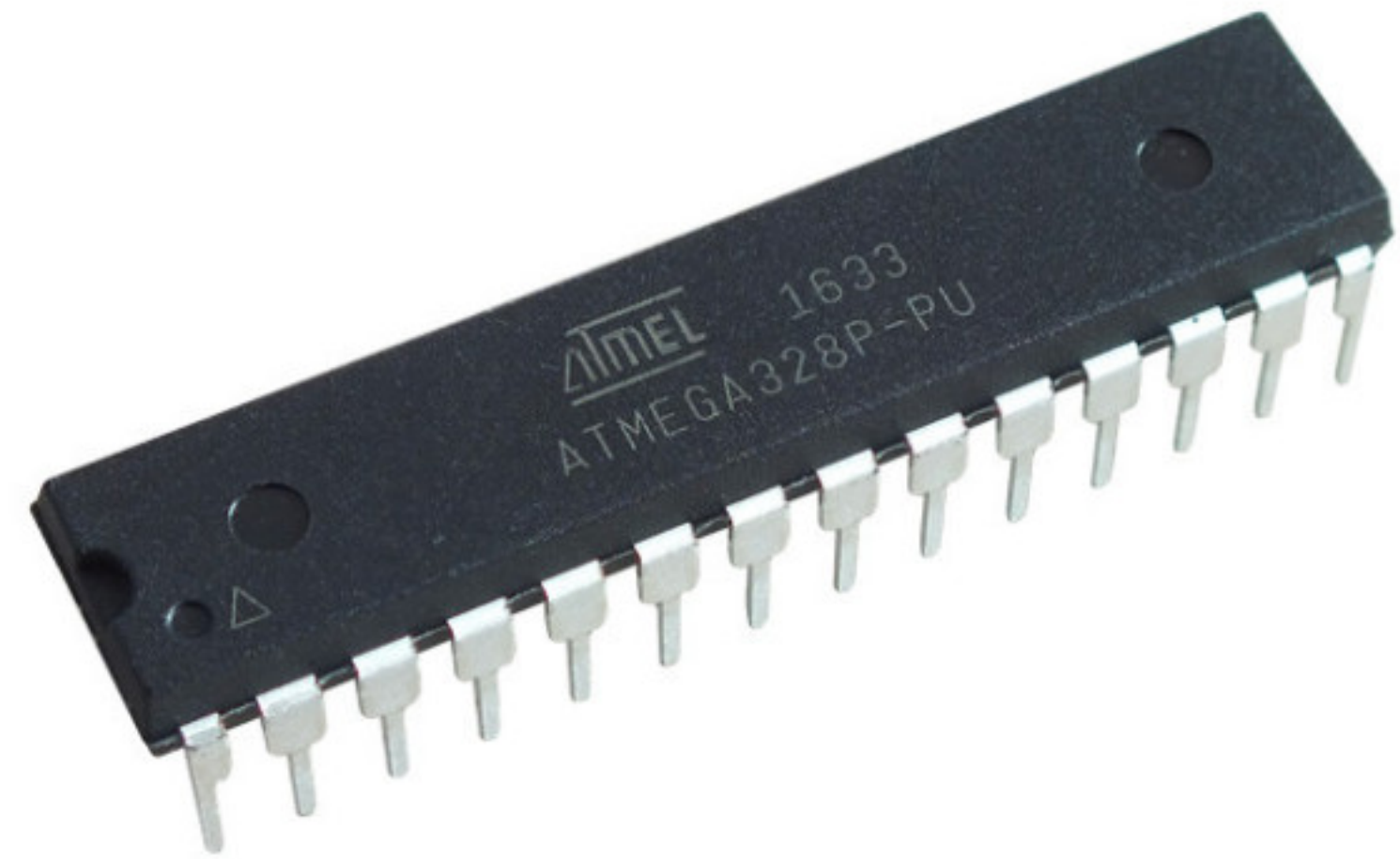
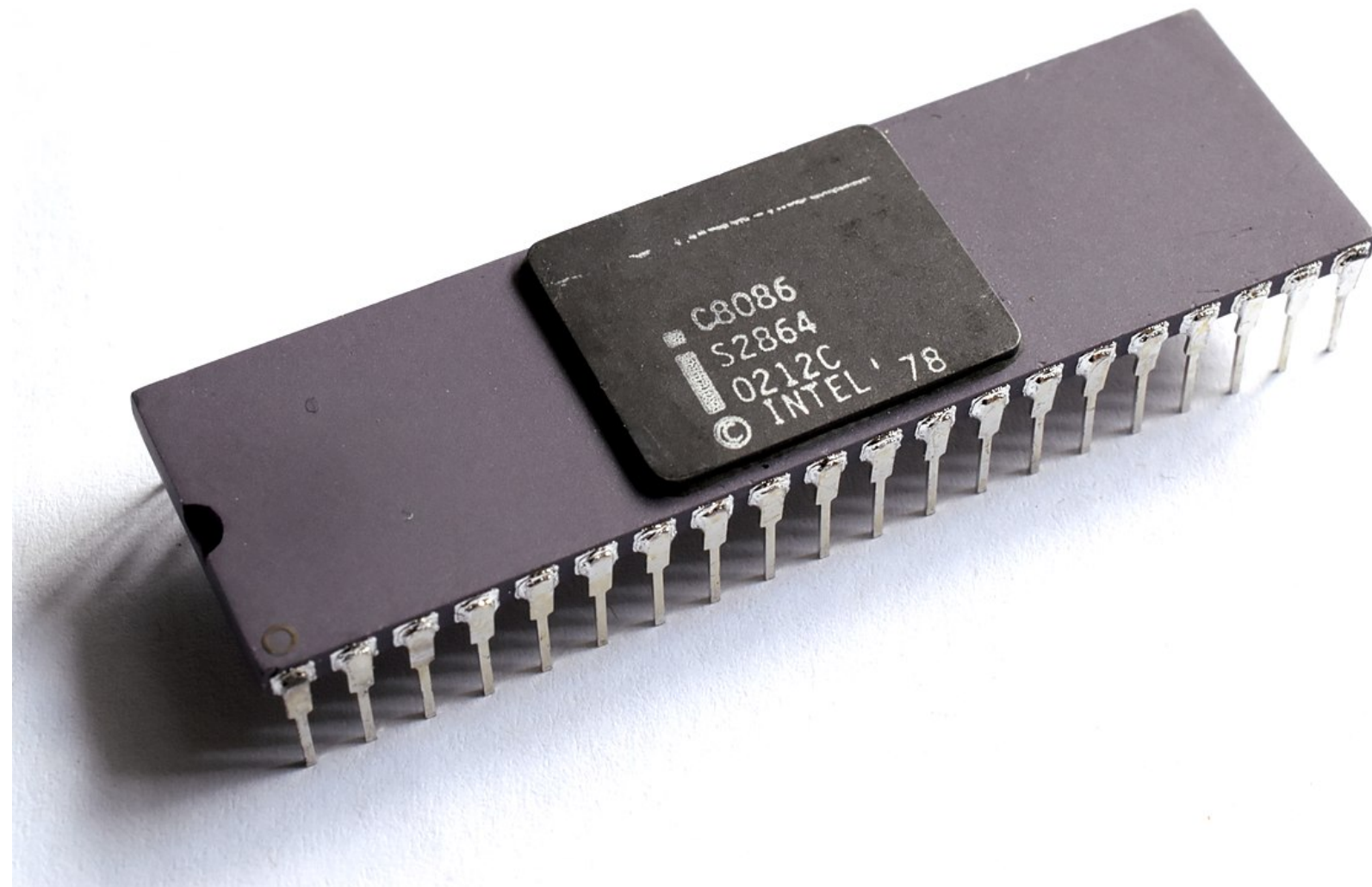


giacomovallorani

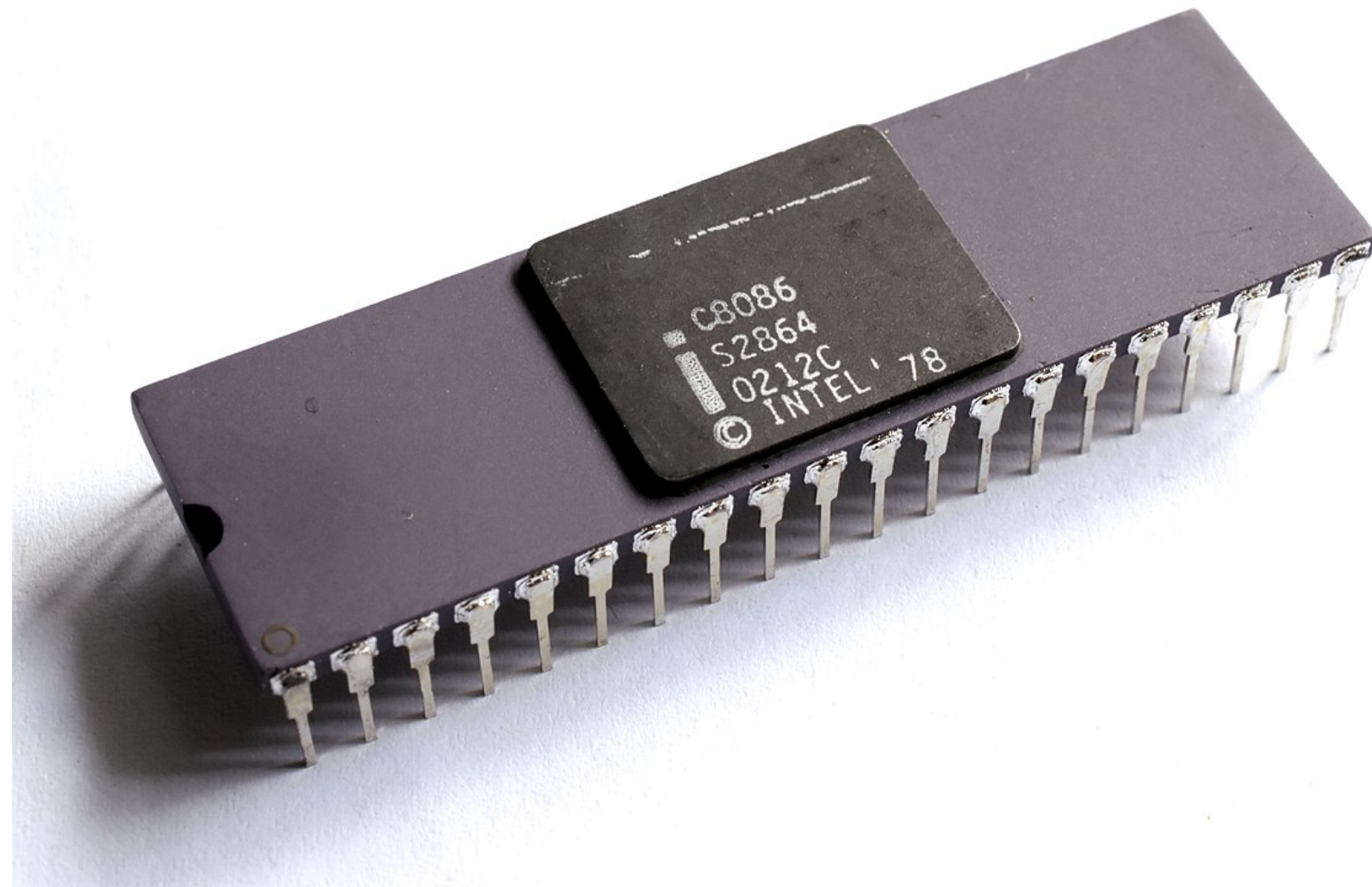
# 1 Programmazione di microcontrollori



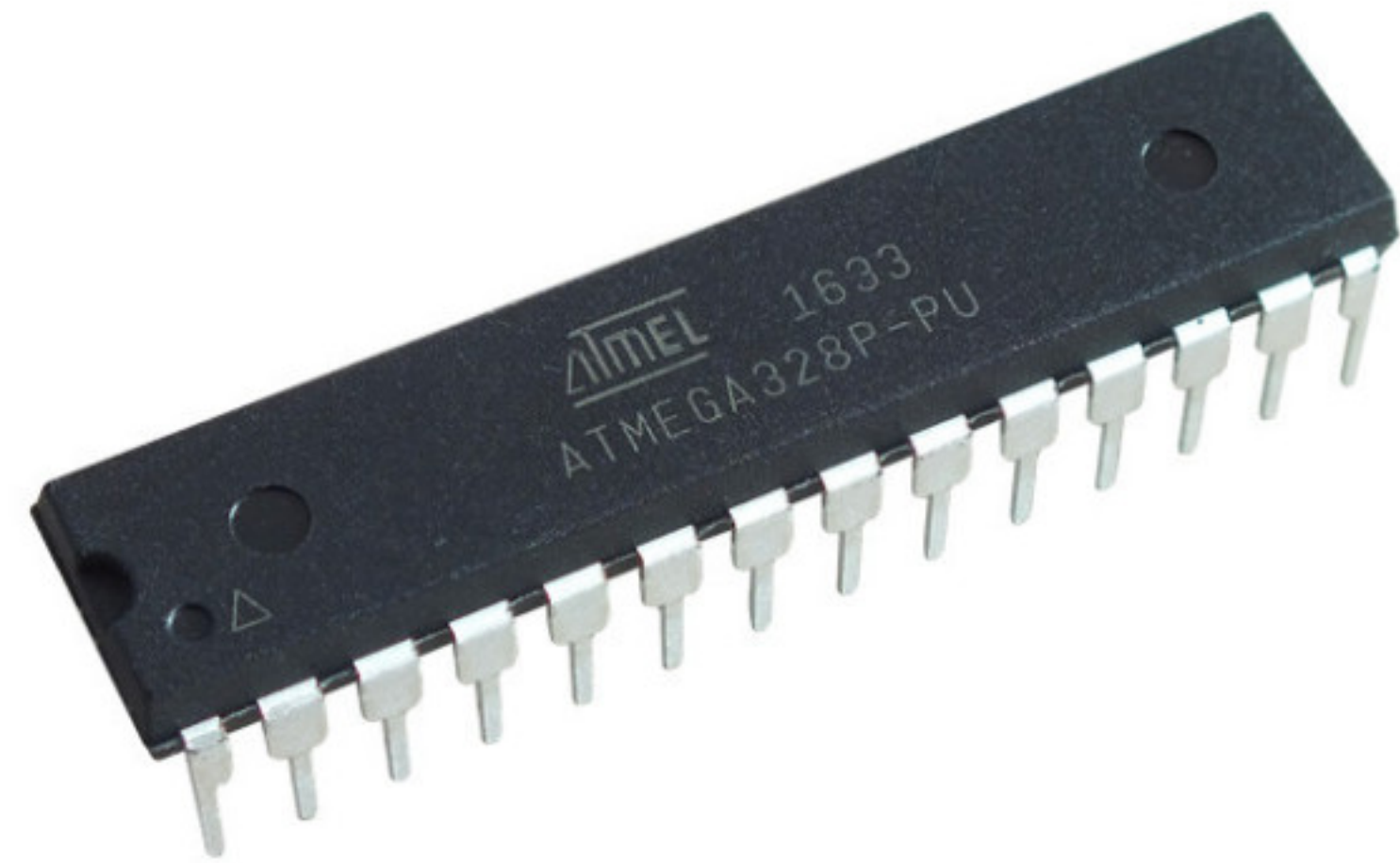
# Microprocessore vs Microcontrollore



# Microprocessore vs Microcontrollore

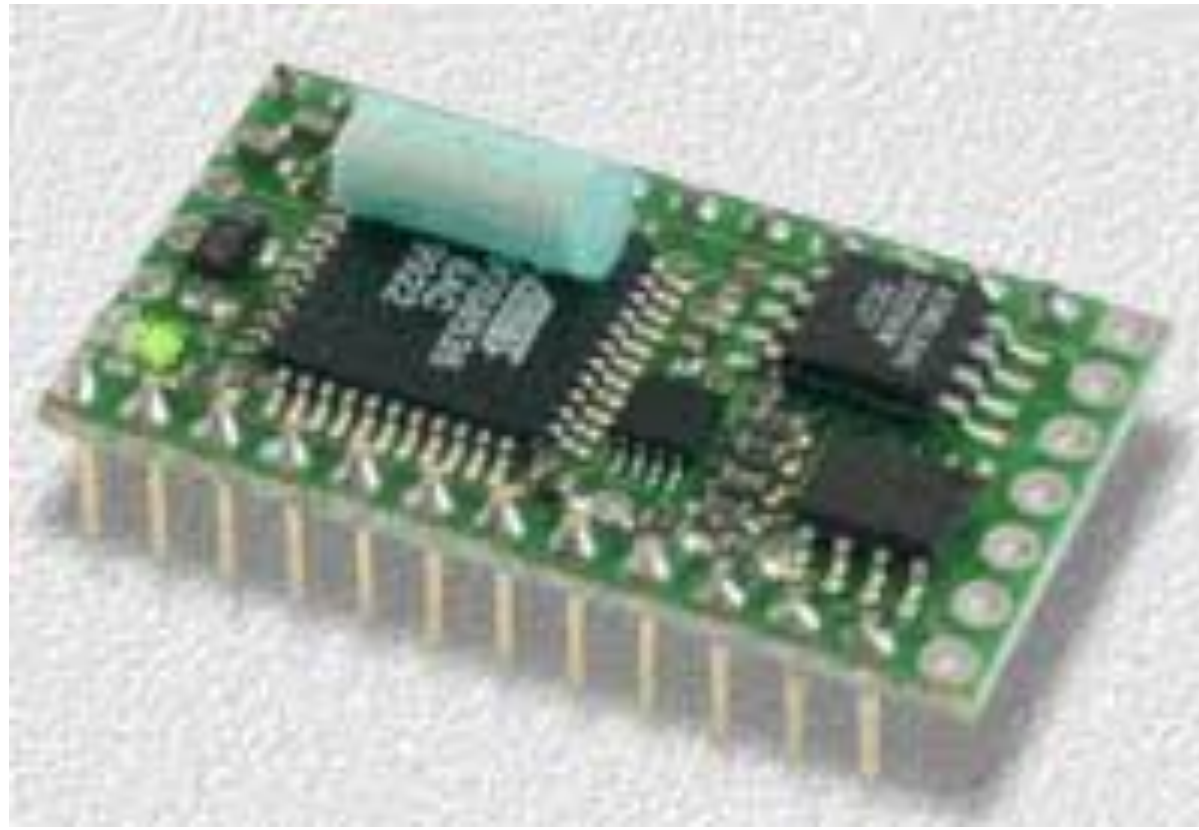


- Solo CPU
- Multitasking
- Consumi in Watt
- Costoso

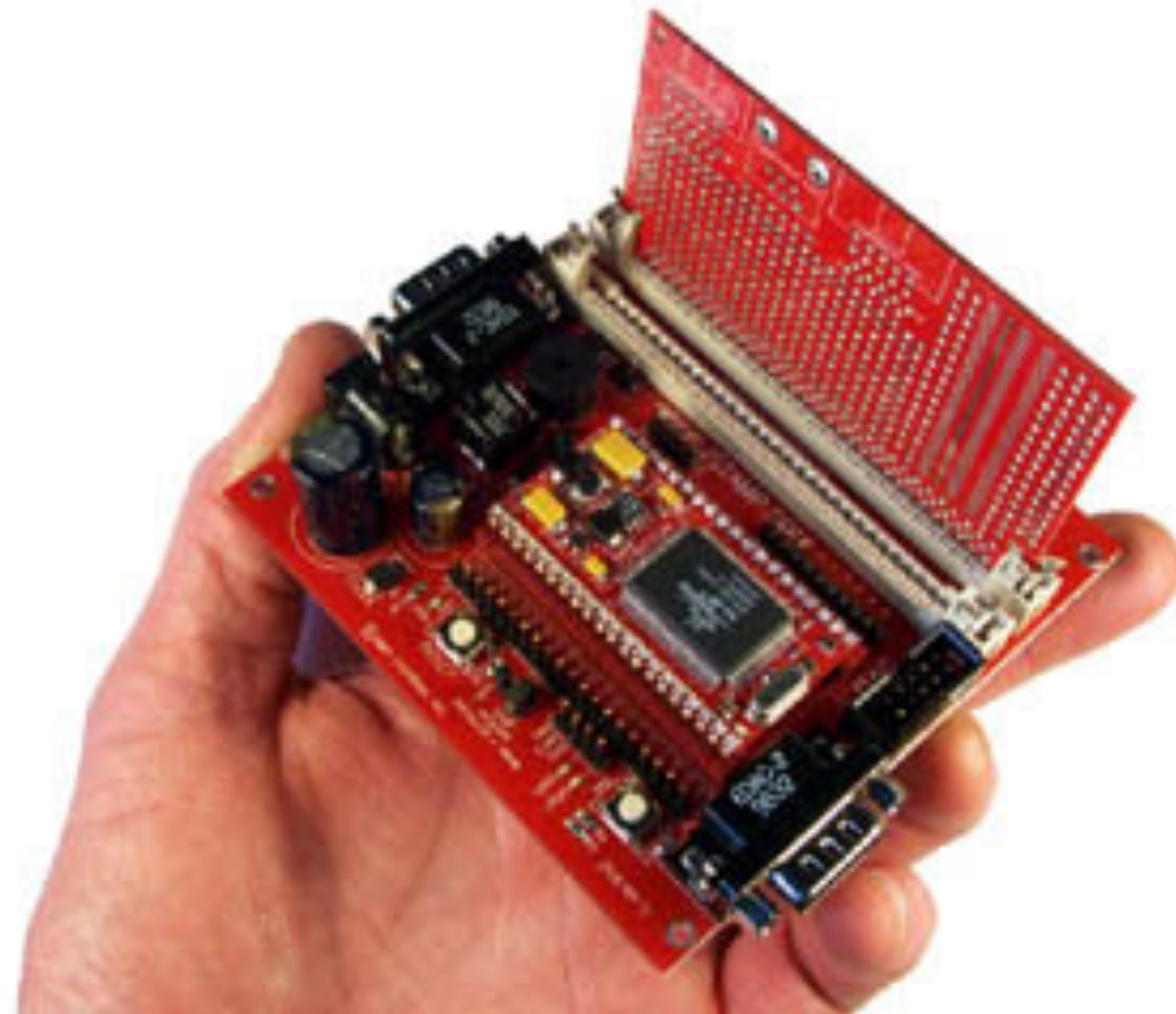


- CPU + memoria + periferiche
- Single task
- Consumi in Milliwatt
- Economico

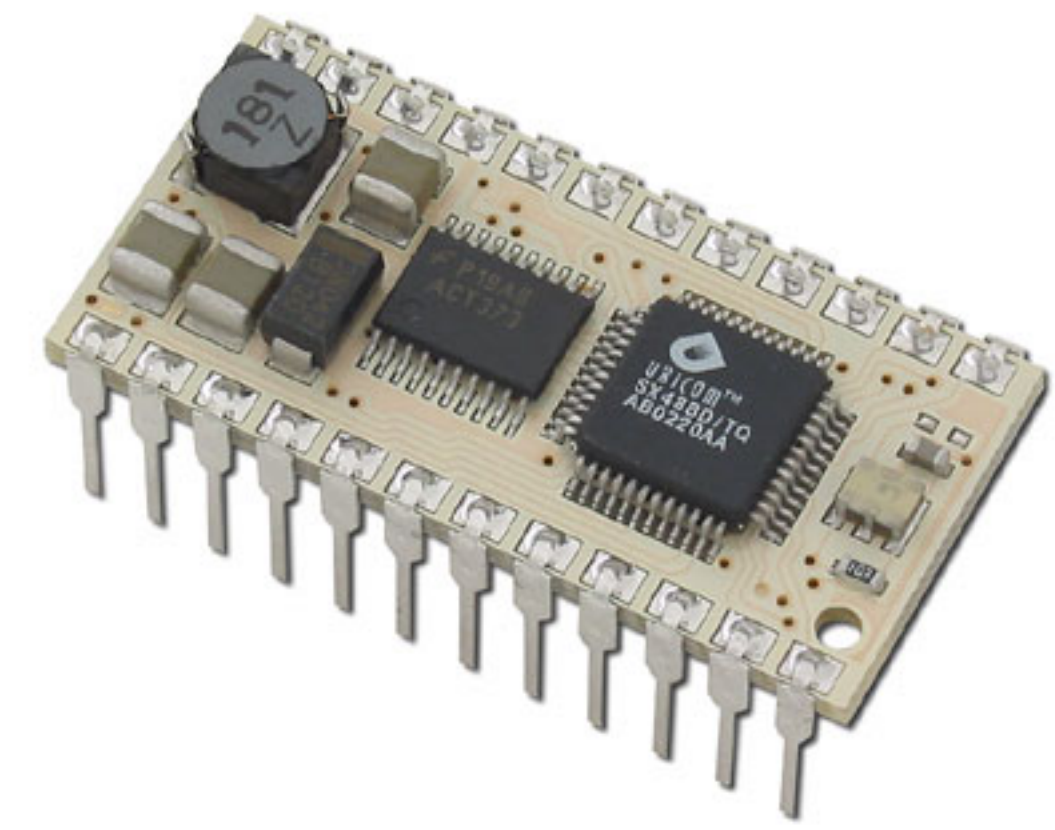
# Il mondo prima di Arduino



Netmedia BasicX-24



Systronix JStamp



Parallax Javelin Stamp

# La democratizzazione dell'hardware

```
Blink | Arduino 1.8.5

Blink §

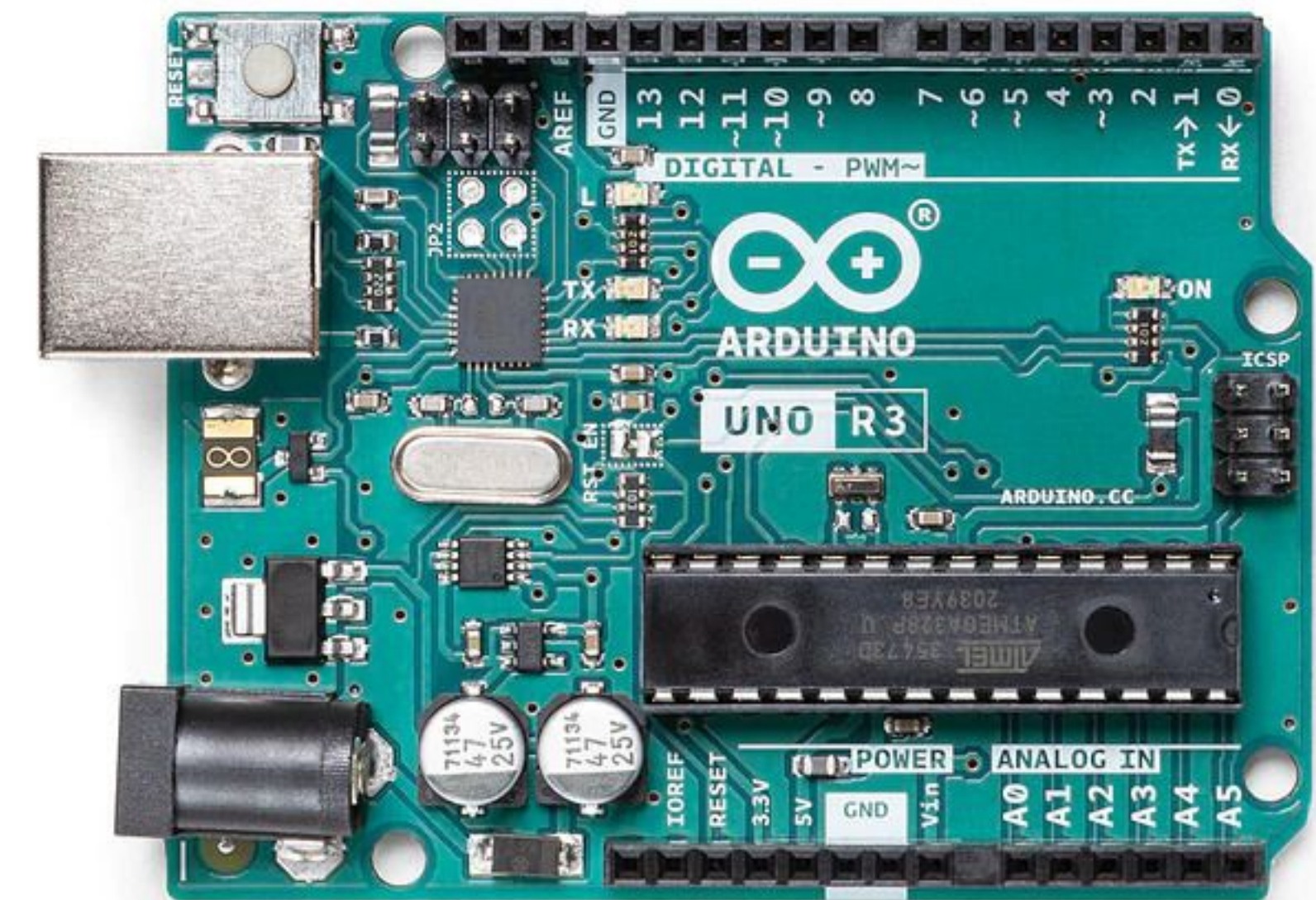
This example code is in the public domain.

http://www.arduino.cc/en/Tutorial/Blink
*/

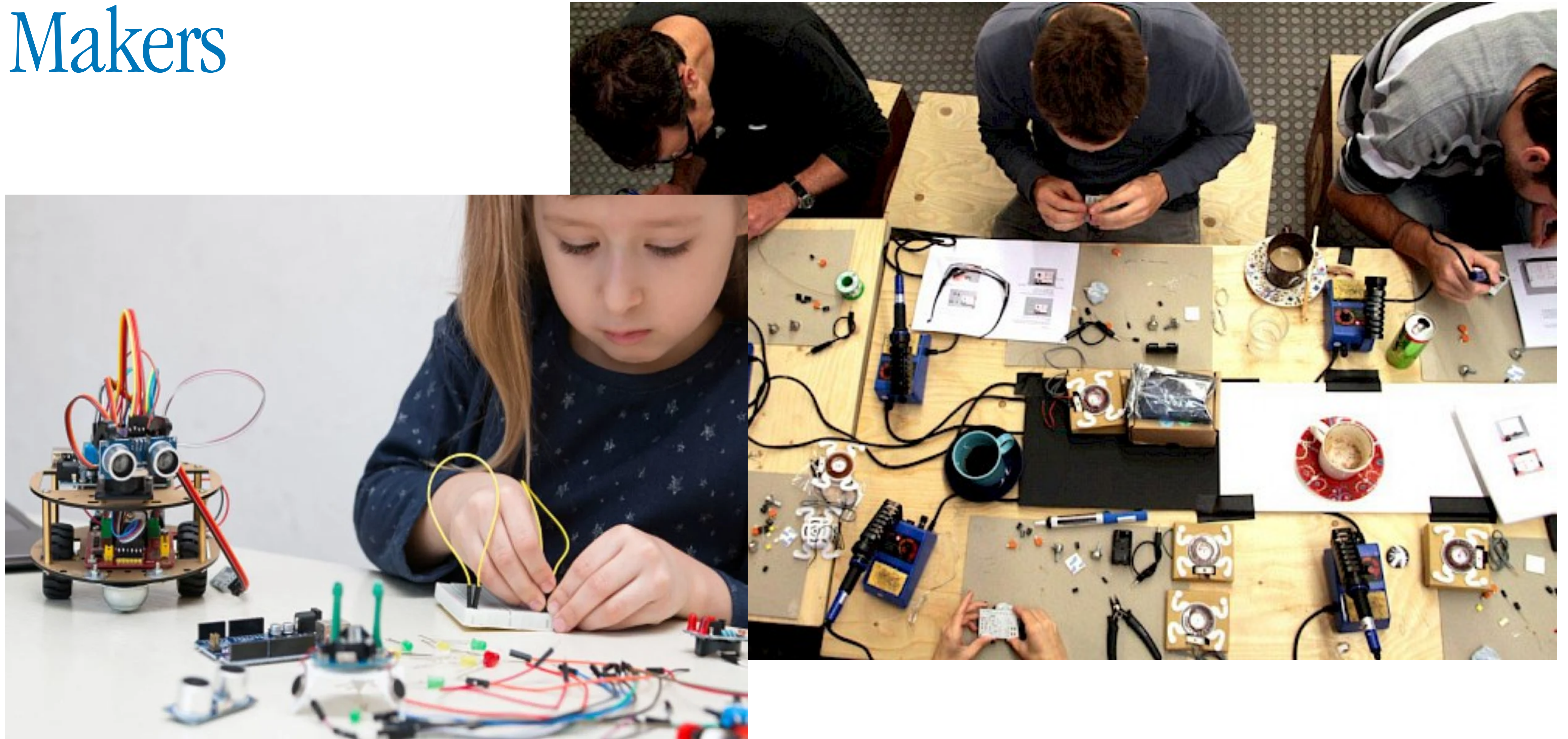
// the setup function runs once when you press reset or power the board
void setup() {
  // initialize digital pin LED_BUILTIN as an output.
  pinMode(LED_BUILTIN, OUTPUT);
}

// the loop function runs over and over again forever
void loop() {
  digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the voltage level)
  delay(1000);                      // wait for a second
  digitalWrite(LED_BUILTIN, LOW);  // turn the LED off by making the voltage LOW
  delay(1000);                      // wait for a second
}

32 Arduino/Genuino Uno on COM1
```



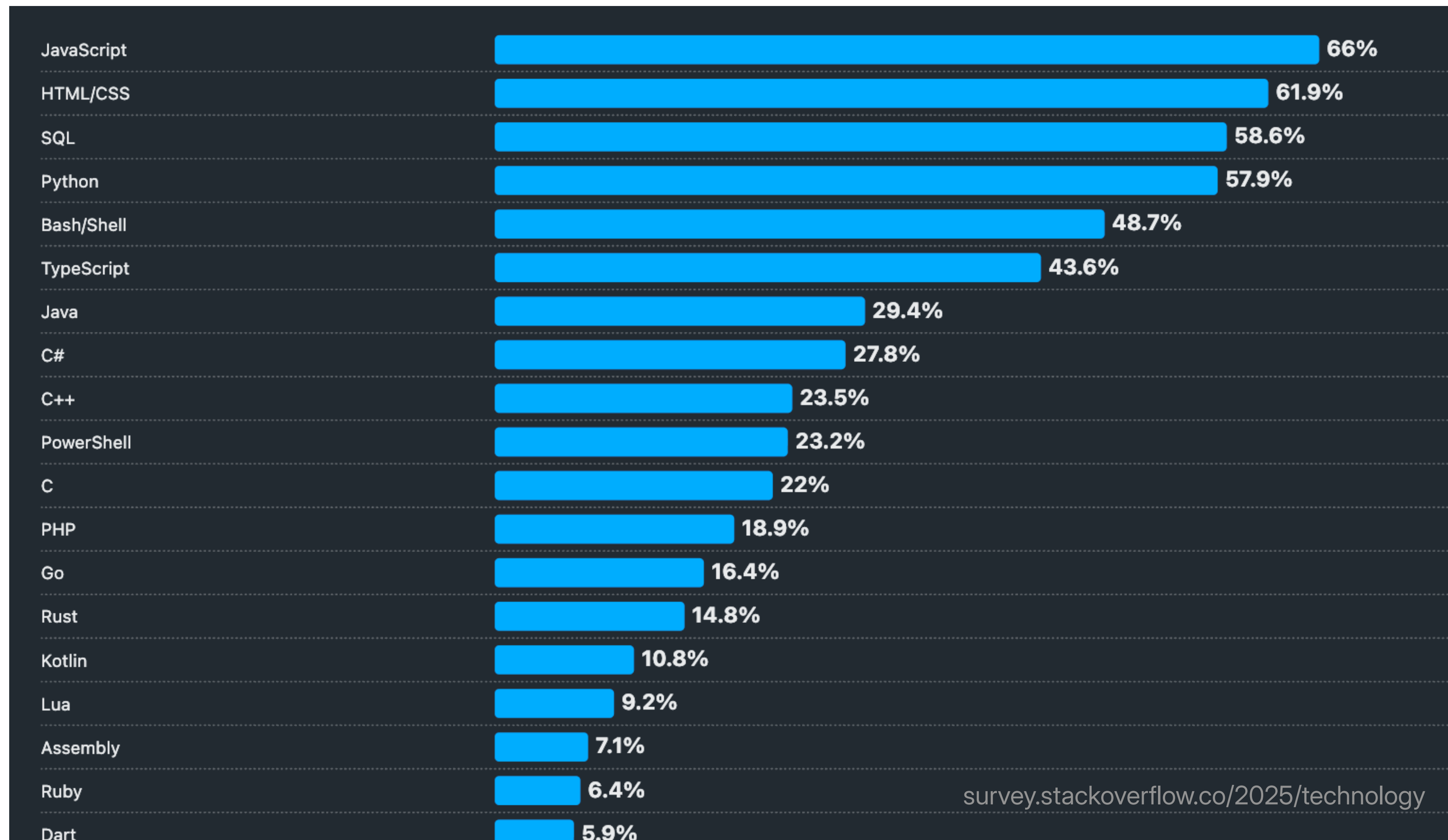
# Makers



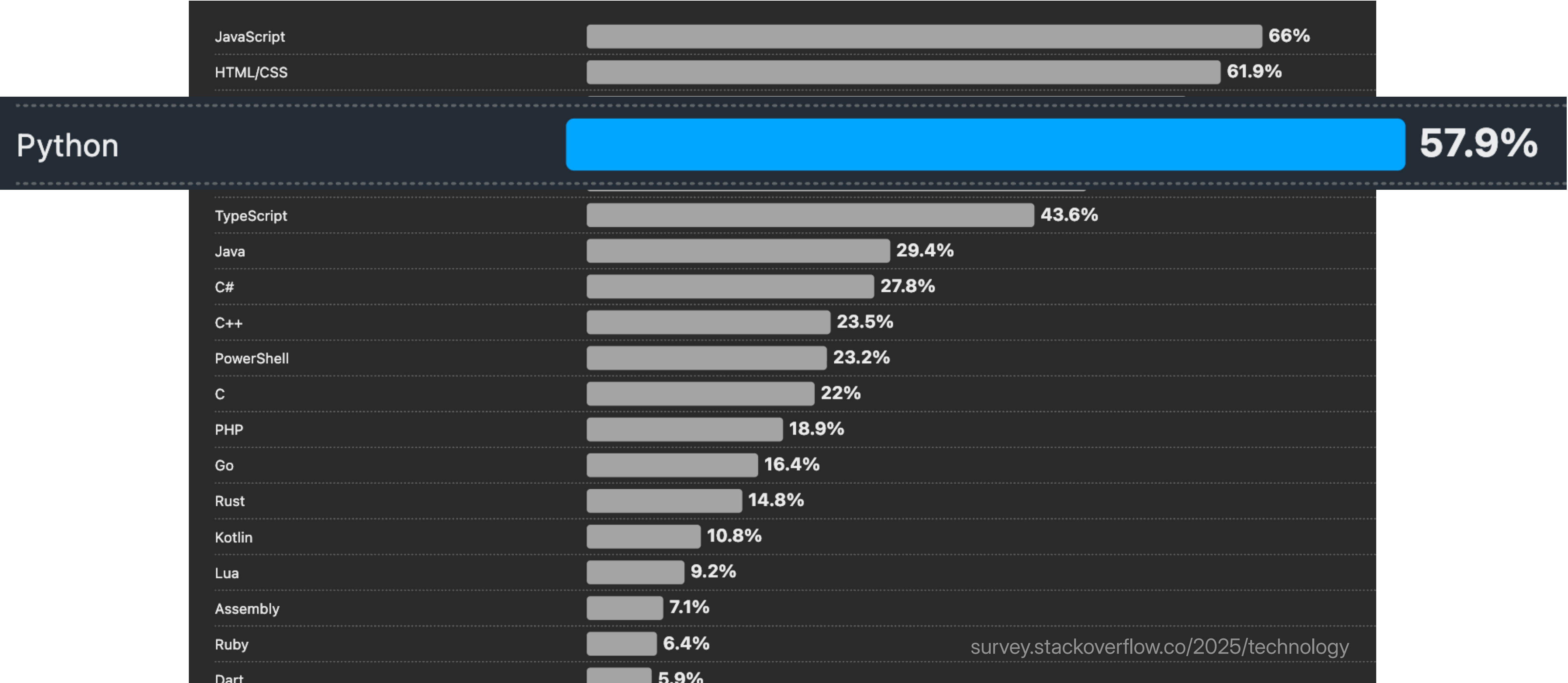


# Perché (Micro)Python?

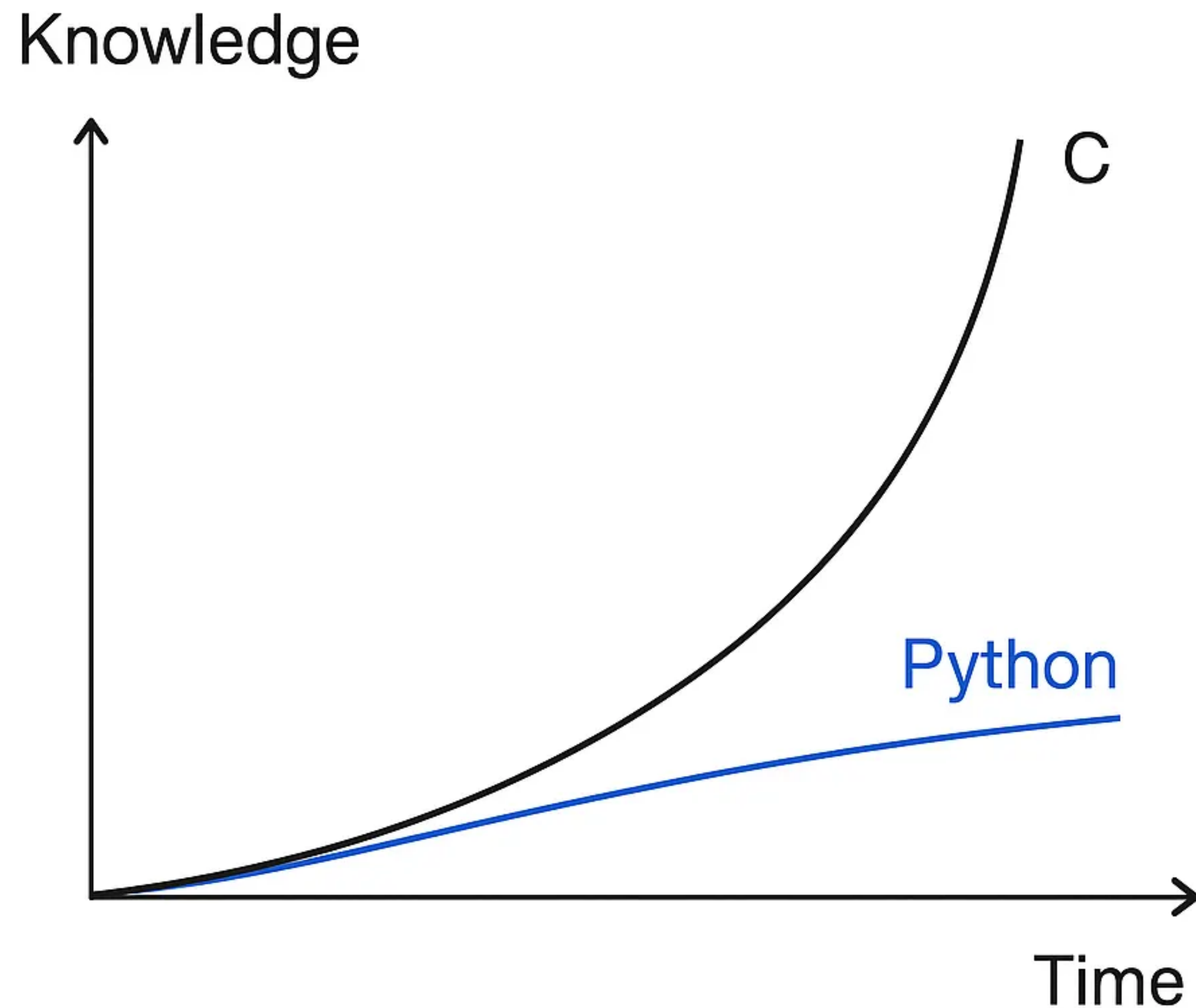
# Adozione



# Adozione



# Curva di apprendimento



~~Puntatori~~

~~Gestione della memoria~~

~~Compilazione~~

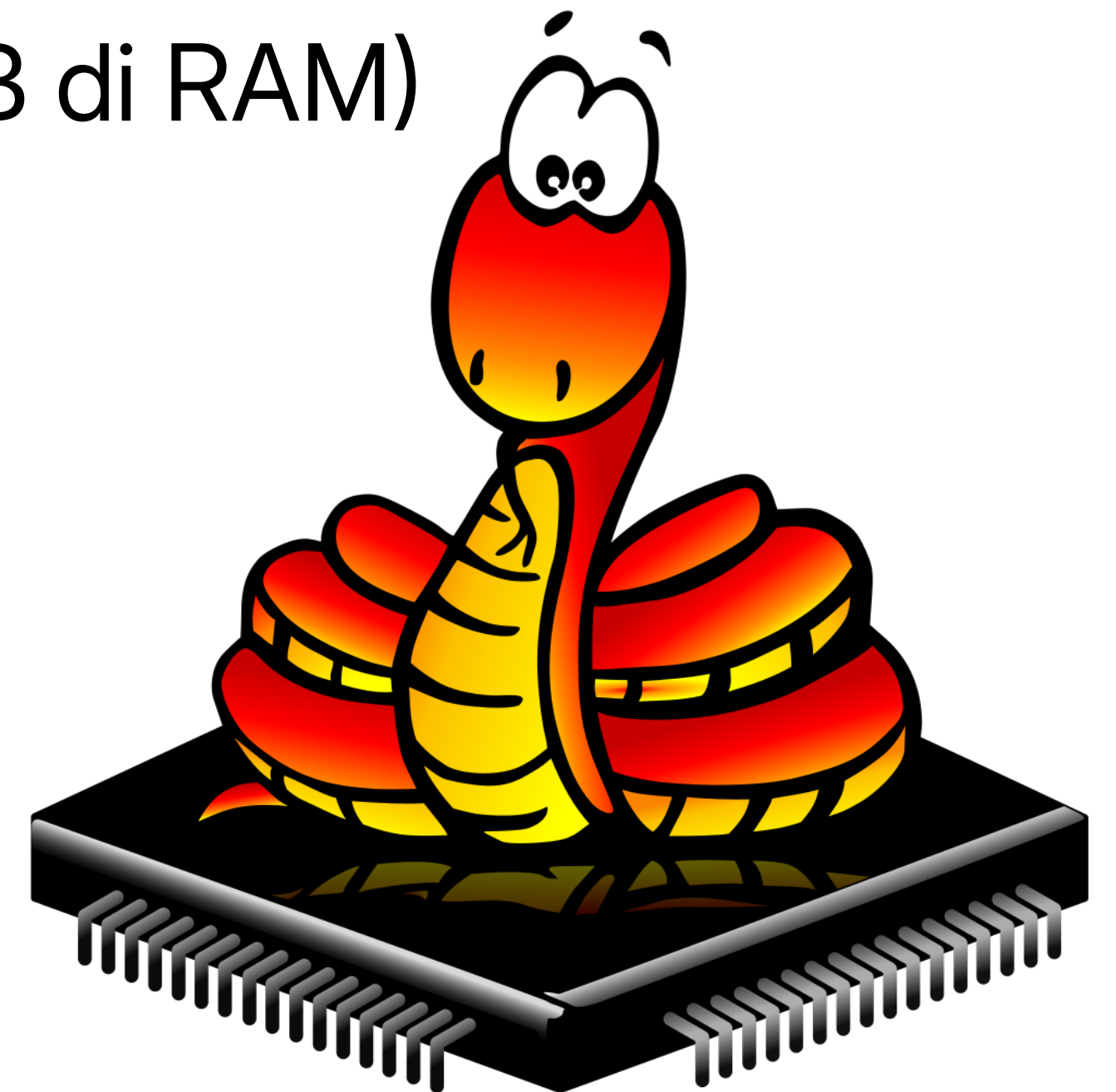
list/dict/tuple

Garbage collector

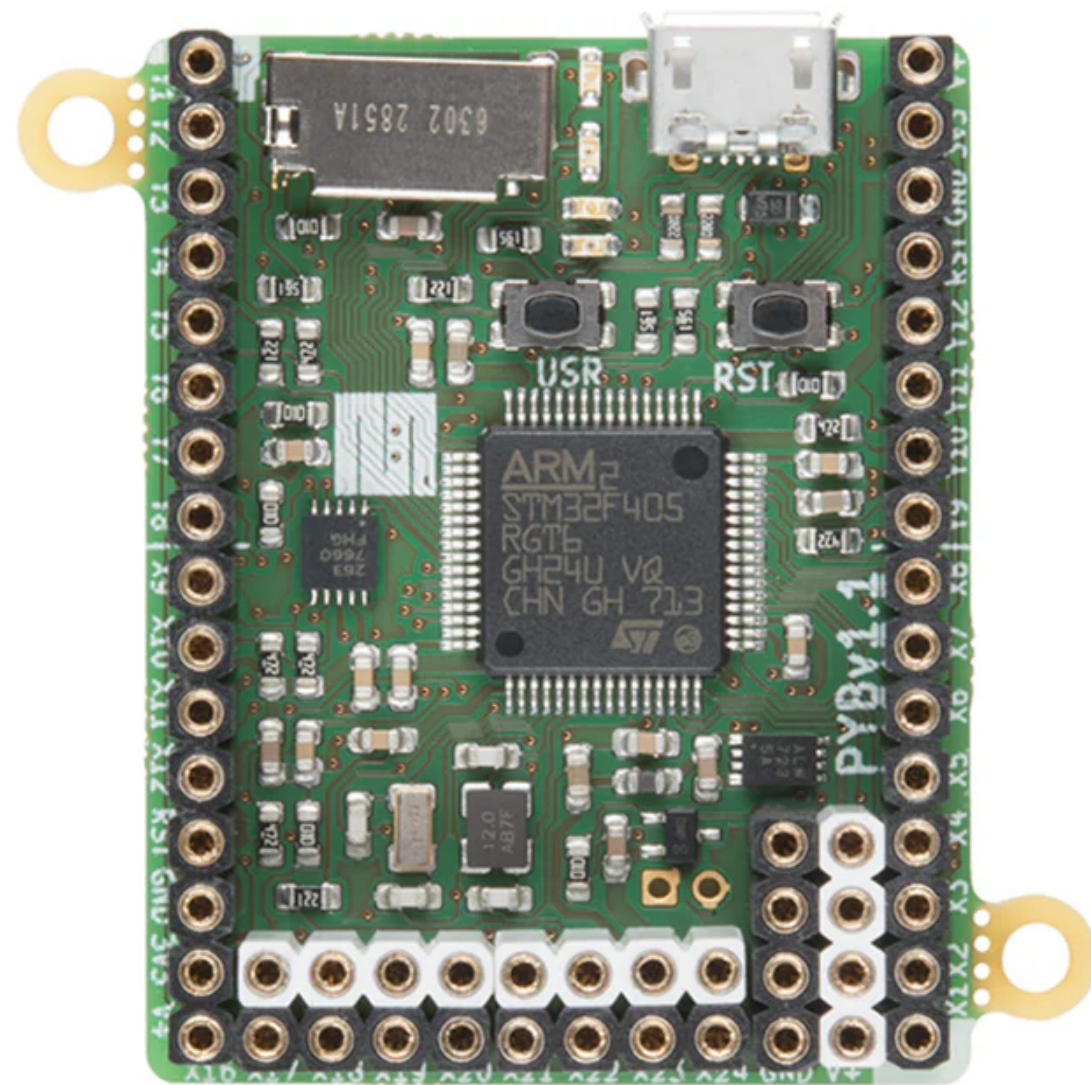
try/except

# MicroPython

- Progetto Kickstarter(2013) by Damien George
- Python 3.x per microcontrollori
- Progettato per essere **efficiente** con le risorse (minimo 8KB di RAM)
- Progettato per essere eseguito **bare metal**
- Libreria **machine** per accesso hardware / GPIO
- Punta alla compatibilità con librerie CPython
- Open source: MIT license



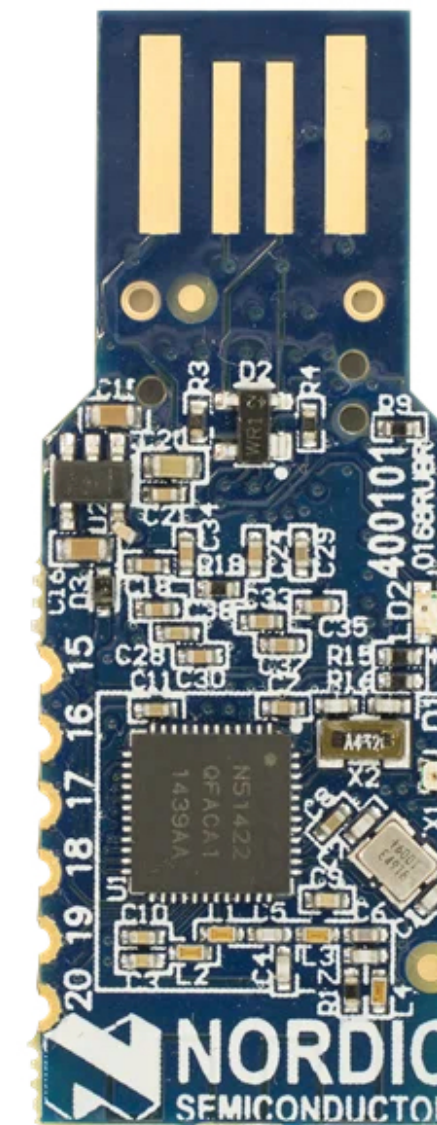
# Board compatibili



PyBoard (STM32)



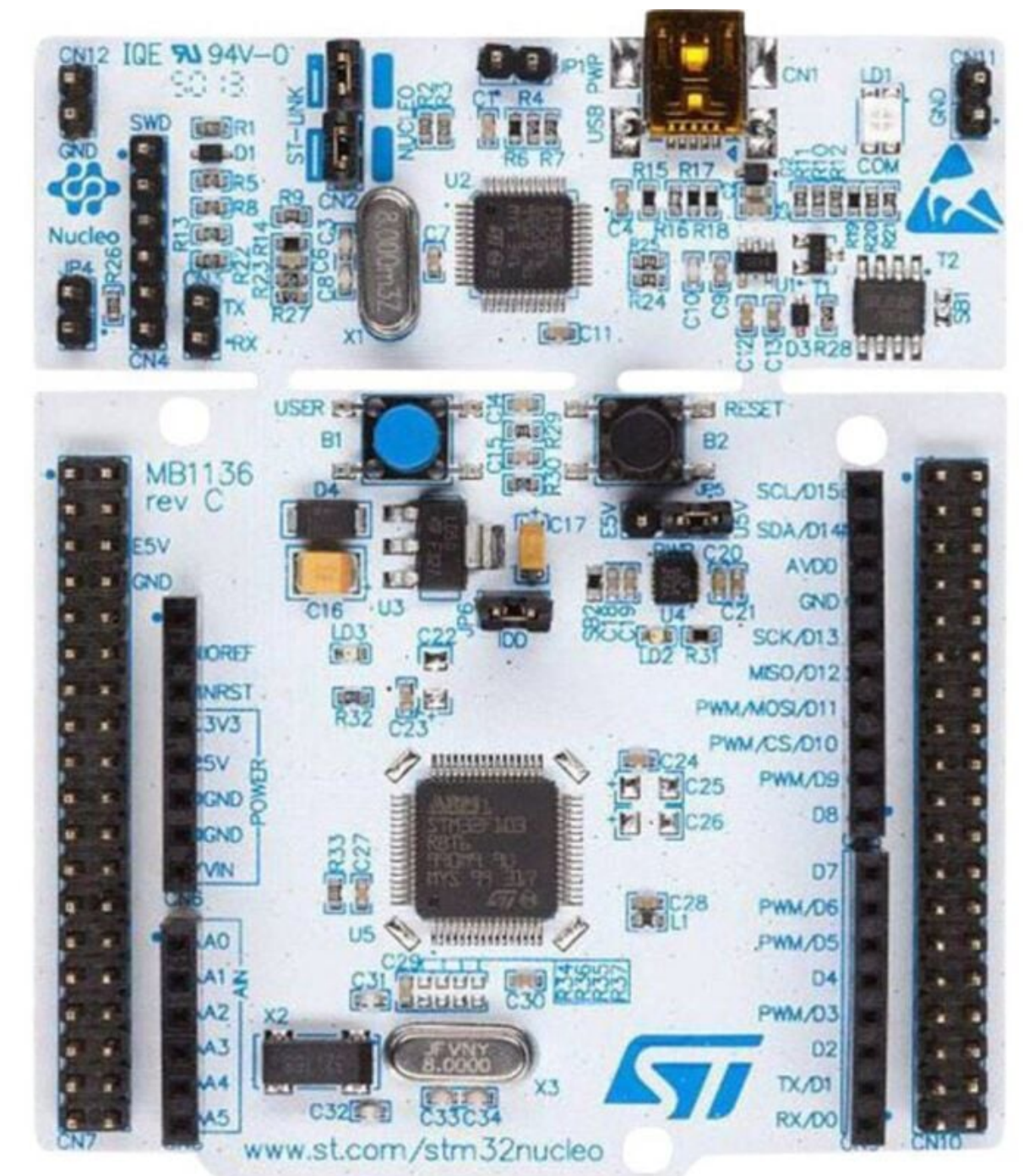
ESP32/ESP8266



pca100XX

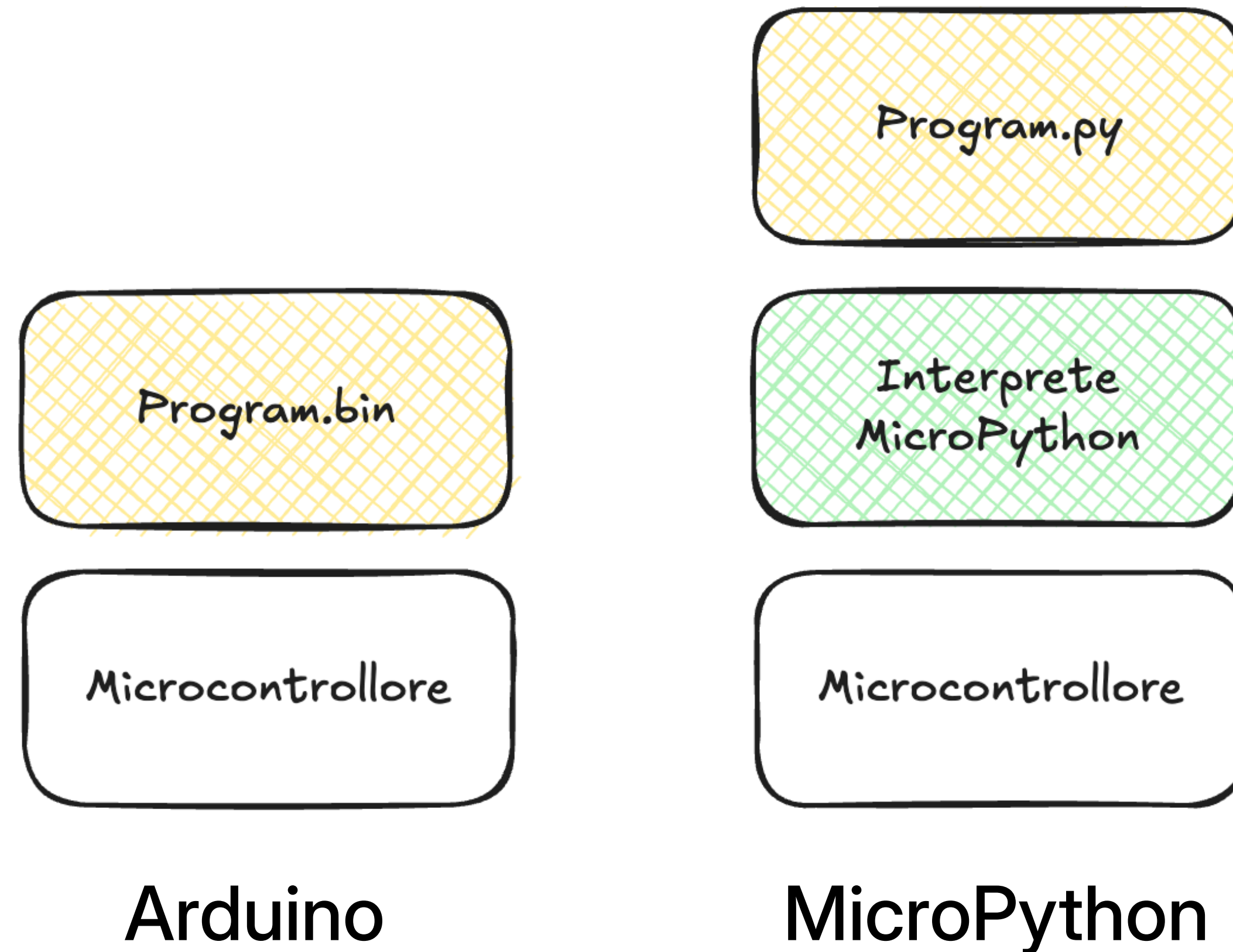


Raspberry Pi PICO (RP2040)



STM32

# Arduino vs MicroPython



Read

Evaluate

Print

Loop

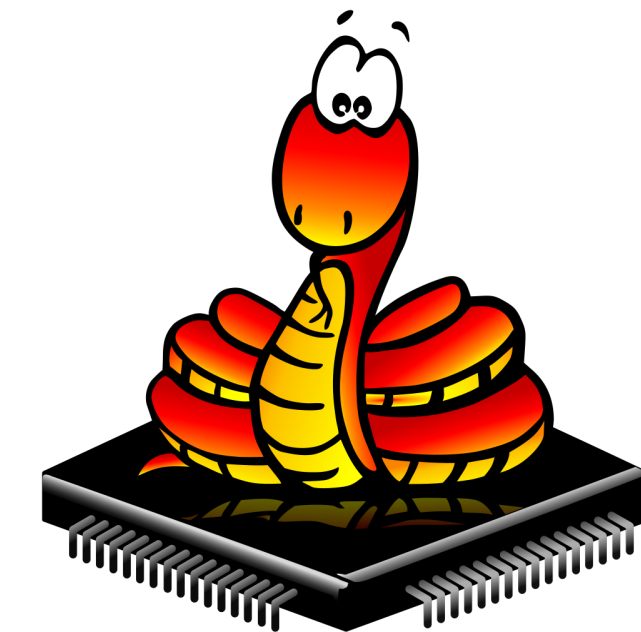


Read



```
vallasc — Python — 37x8
>>> print(senso_della_vita)
```

Evaluate



Print



```
vallasc — Python — 37x8
>>> print(senso_della_vita)
42
>>>
```



Loop

# Package Management

```
import mip
# Installa l'ultima versione dei "pkgname" (and dependencies)
mip.install("pkgname")
# Installa una versione specifica
mip.install("pkgname", version="x.y")

# Installa una libreria custom
mip.install("http://example.com/x/y/foo.py")
# Installa una libreria custom sotto forma di bytecode
mip.install("http://example.com/x/y/foo.mpy")
```

# Moduli

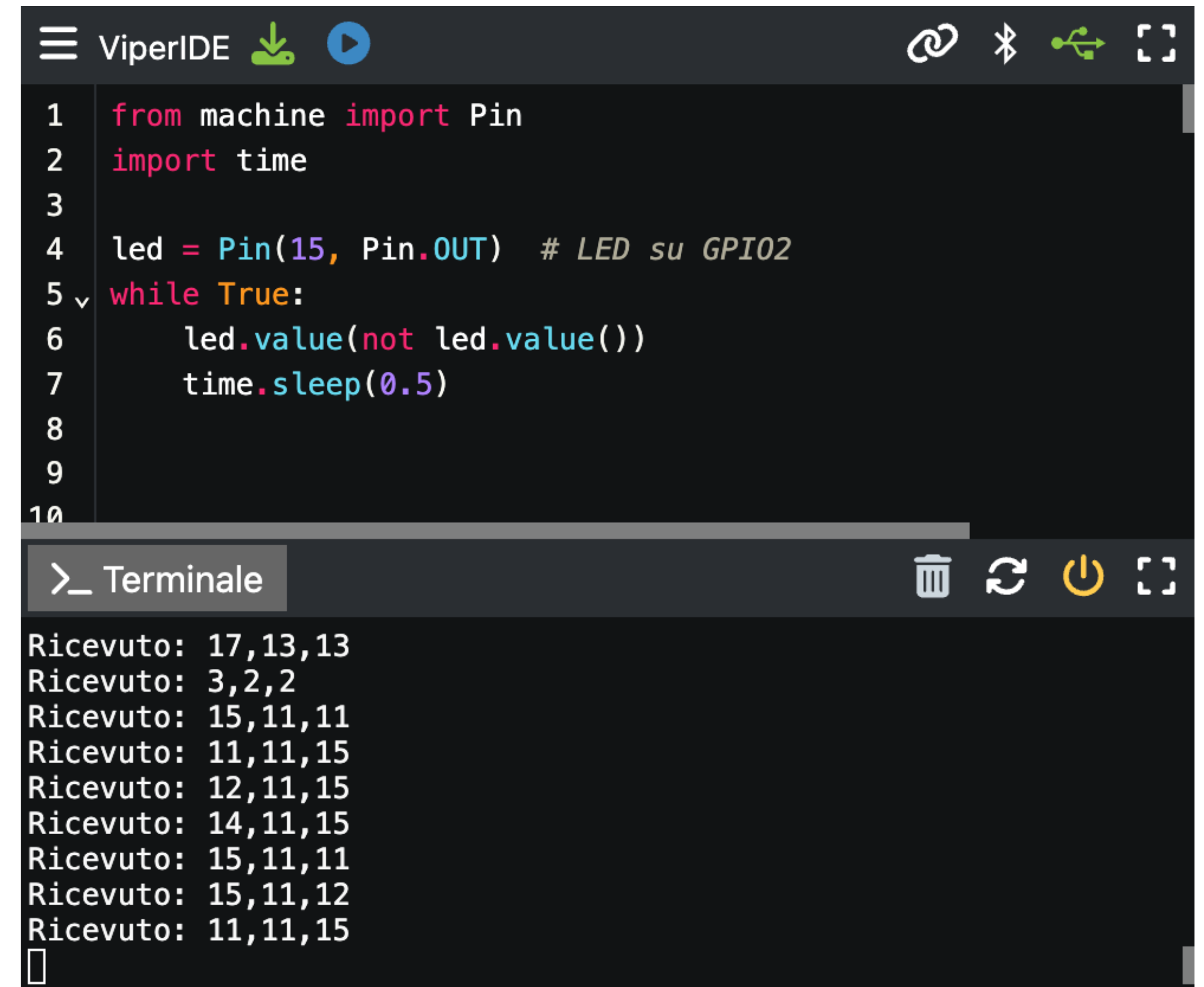
- Moduli built-in che replicano le funzionalità di Python (es. os, time)
- Moduli specifici per l'hardware sottostante (es. bluetooth, machine, network)
- Moduli di utilità (es. umqtt, dht)

```
import dht  
import machine
```

```
sensor = dht.DHT22(machine.Pin(4))  
sensor.measure()  
print("Temperatura:", sensor.temperature(), "°C")
```

# Ambiente di sviluppo

- Linea di comando **mpremote**
- **Thonny IDE**
- **VSCode** + micropython-stubs  
+ MPRemote
- **ViperIDE** - [viper-ide.org](http://viper-ide.org)



The screenshot displays the ViperIDE application window. The top bar shows the title 'ViperIDE' and several icons for file operations and connectivity. The main editor area contains a Python script with the following code:

```
1 from machine import Pin
2 import time
3
4 led = Pin(15, Pin.OUT) # LED su GPIO2
5 while True:
6     led.value(not led.value())
7     time.sleep(0.5)
8
9
10
```

Below the editor is a terminal window titled '>\_ Terminale'. It shows a series of received data packets, each consisting of three integers separated by commas:

```
Ricevuto: 17,13,13
Ricevuto: 3,2,2
Ricevuto: 15,11,11
Ricevuto: 11,11,15
Ricevuto: 12,11,15
Ricevuto: 14,11,15
Ricevuto: 15,11,11
Ricevuto: 15,11,12
Ricevuto: 11,11,15
```

The terminal window also includes icons for clearing the content, refreshing, and power.

# Blink

```
from machine import Pin
import time

led = Pin(15, Pin.OUT) # LED su GPIO15
while True:
    led.value(not led.value())
    time.sleep(0.5)
```

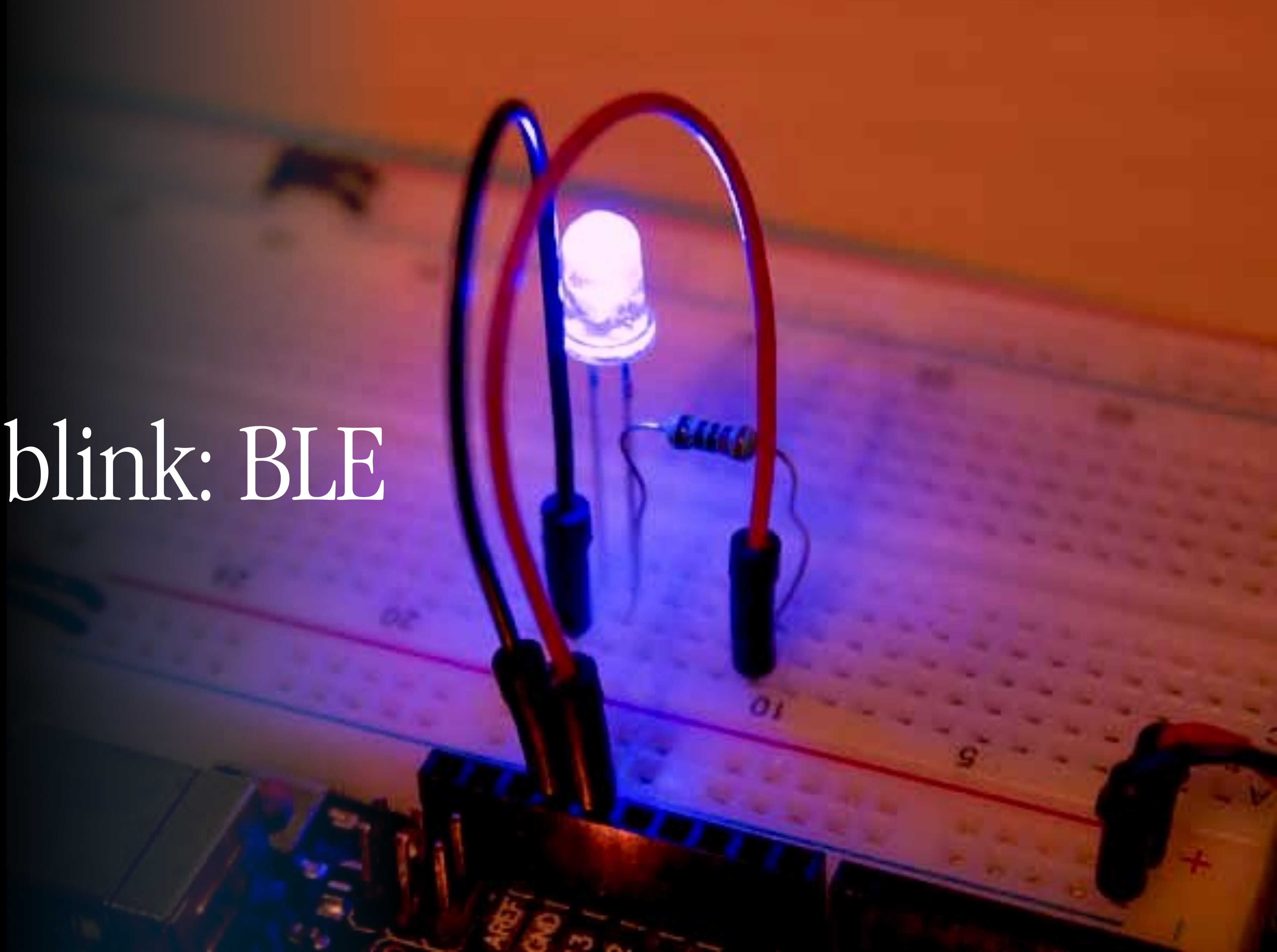
# Non è tutto oro quel che luccica

- Prestazioni inferiori a C/C++:
  - il codice è più lento, anche 5–10 volte.
- Maggiore utilizzo della memoria
  - Interprete + programma .py (o .mpy)
  - Garbage collector
- Meno documentazione



*MicroPython = sviluppo più rapido*  
*C/C++ = codice ottimizzato e più veloce in esecuzione*

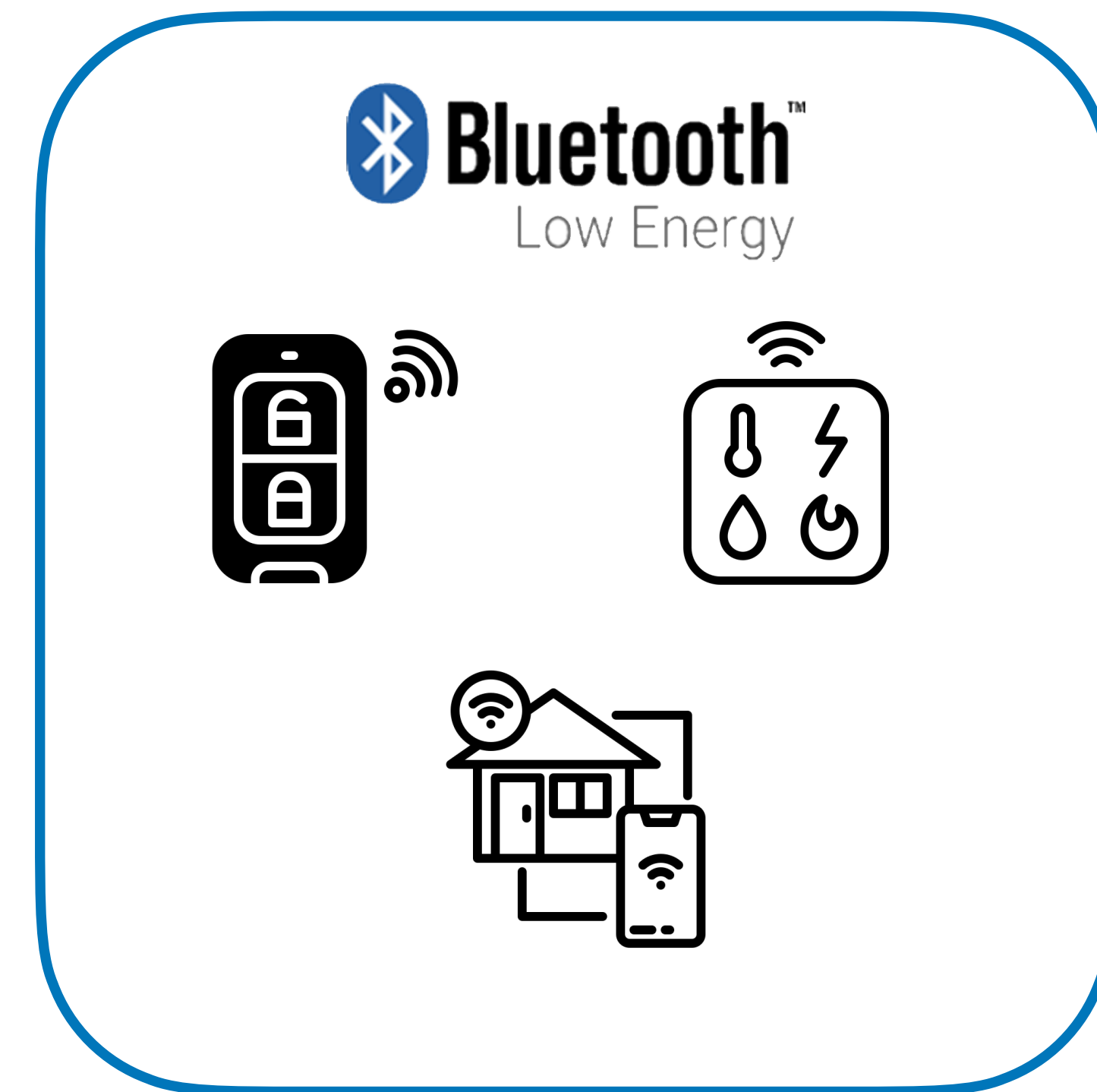
Non solo blink: BLE



# Cos'è il Bluetooth Low Energy



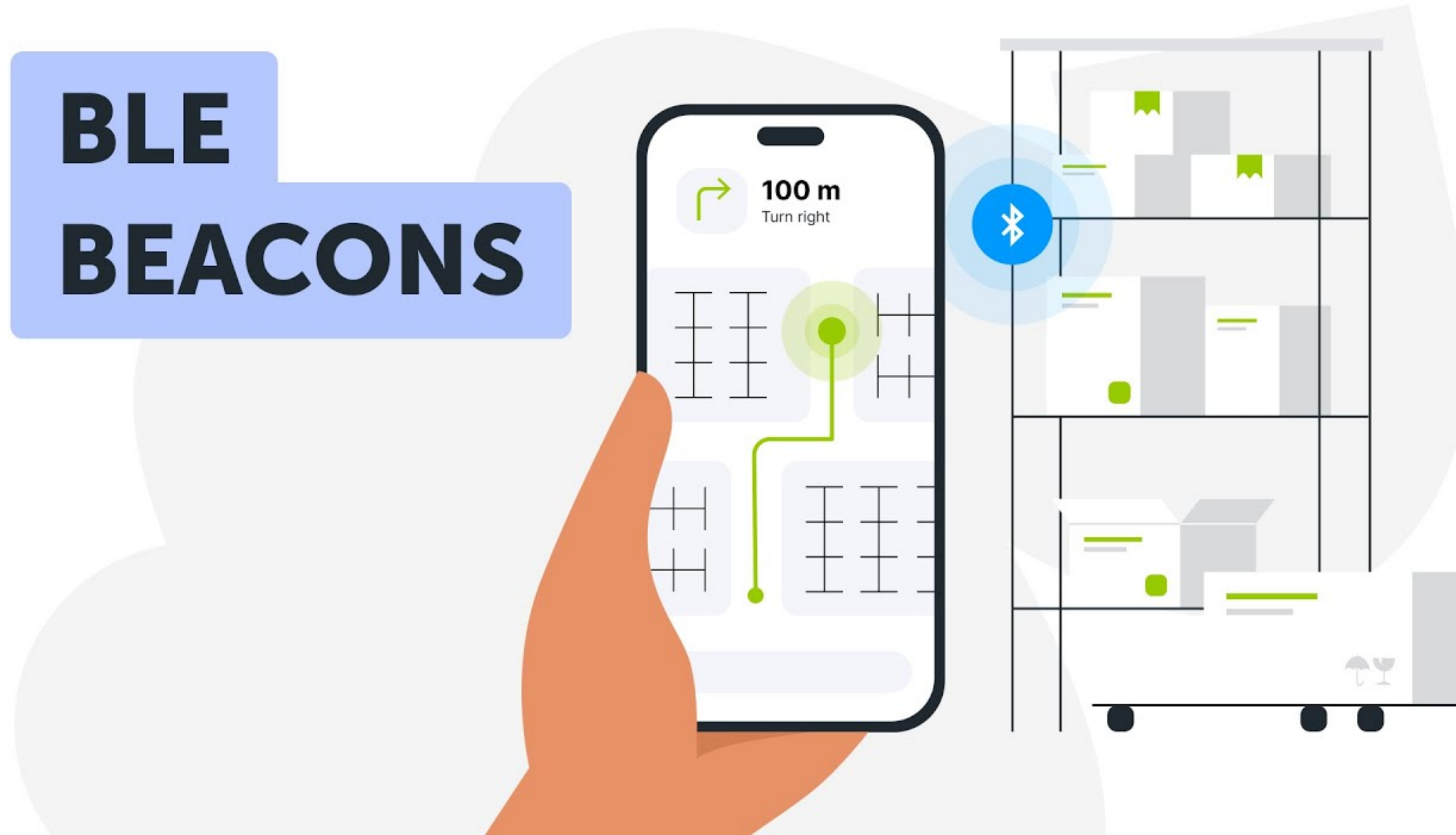
Device wireless che trasmettono rich-content come dati, video e audio.



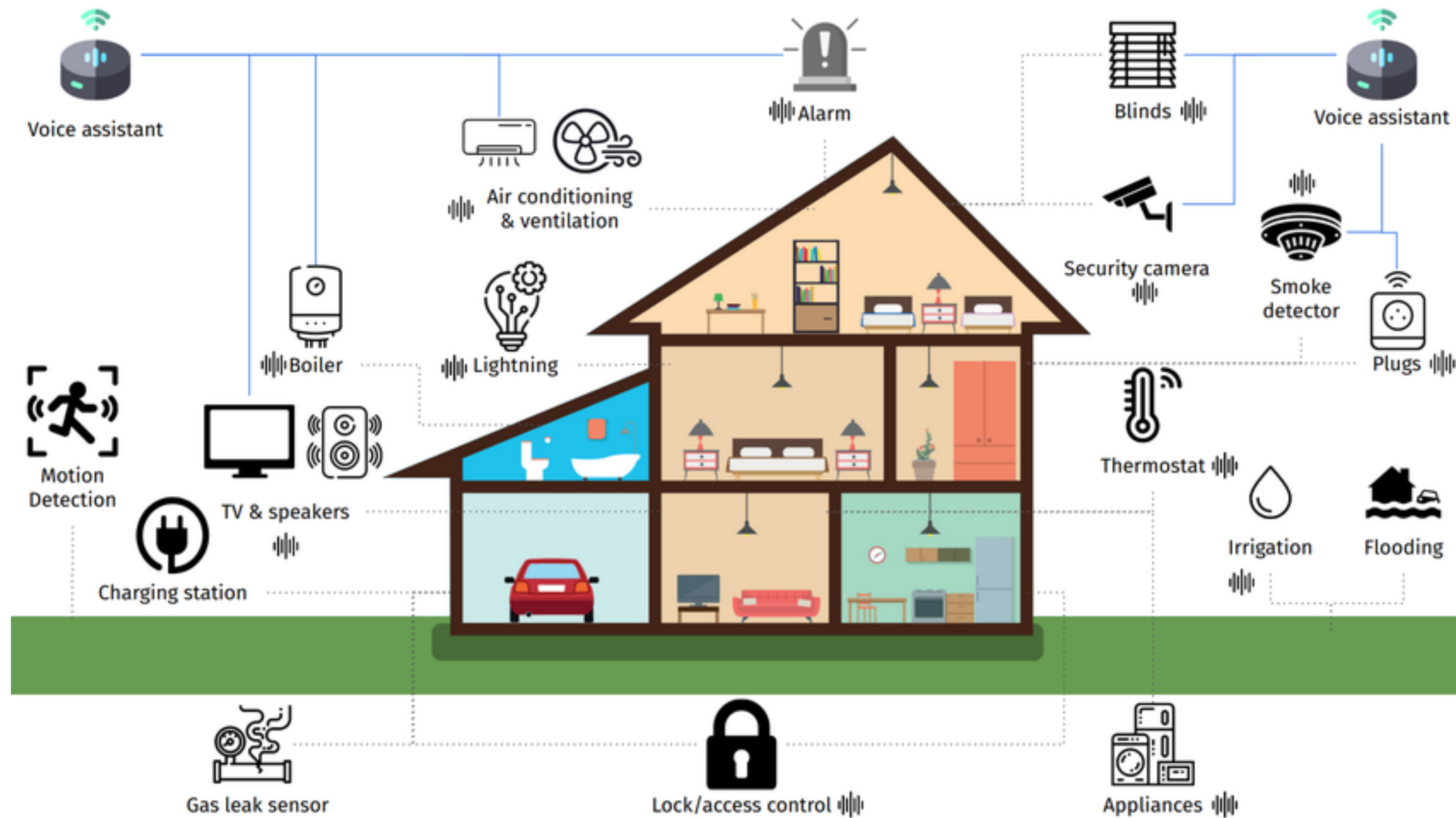
Sensori che inviano pochi dati e low power

# Asset Tracking

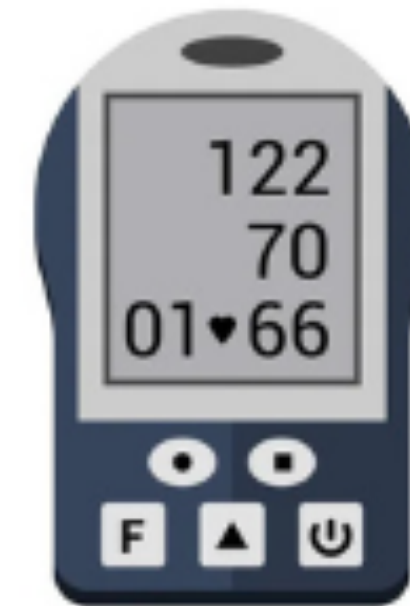
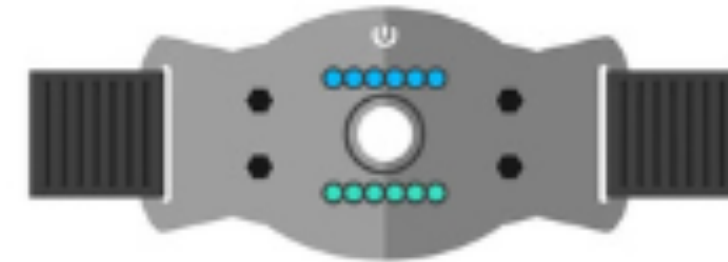
## BLE BEACONS



# Smart Home

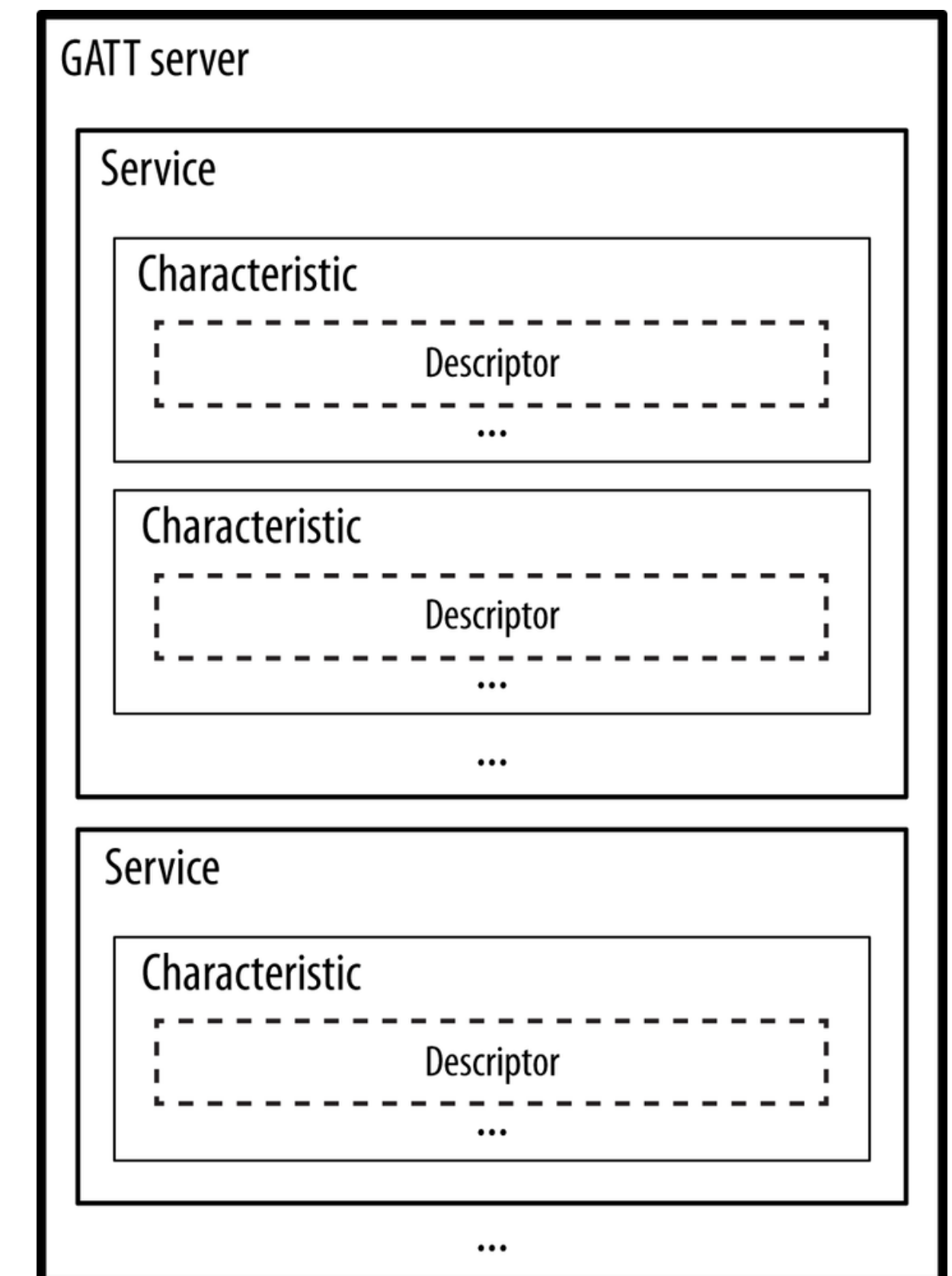


# Wearables



# BLE: Architettura Generale

- Due tipi di dispositivi BLE:
  - **Peripheral:** piccolo dispositivo che espone dati o sensori
    - (es. smartwatch, beacon, termometro).
  - **Central:** dispositivo che legge o controlla i peripheral
    - (es. smartphone, gateway, PC).
- Dopo la connessione, si scambiano dati tramite il protocollo GATT (Generic Attribute Profile).



# Advertising e Scanning

- Il **Peripheral** invia periodicamente pacchetti di advertising
  - I pacchetti contengono informazioni base come nome, UUID, servizi offerti, ecc.
- Il **Central** esegue lo scan, riceve i pacchetti e decide se:
  - Connettersi al dispositivo
  - Leggere i dati direttamente (nel caso di beacon)

# aioble

- **aioble** è una libreria MicroPython asincrona (basata su uasyncio) per gestire il Bluetooth Low Energy
- Fornisce un'API **più semplice e ad alto livello** rispetto al modulo **bluetooth**
- Gestisce automaticamente:
  - Advertising e scanning
  - Connessioni (Central ↔ Peripheral)
  - Servizi e caratteristiche GATT

# Nordic UART Service (NUS)

- È un servizio BLE standard (sviluppato da Nordic Semiconductor) che emula una **seriale UART** via Bluetooth.
- Consente di inviare e ricevere stringhe di testo o dati binari tra due dispositivi BLE.
- Utilizza due caratteristiche:
  - **RX Characteristic**: per ricevere dati (dal Central → Peripheral)
  - **TX Characteristic**: per inviare dati (dal Peripheral → Central)
- Molto usato per debug, comandi remoti o comunicazione tra microcontrollore e smartphone.



DEMO